

Cyber-Physical Systems
and the
Right-Hand Side Problem
—
An informal talk

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Cyber-physical systems and the right-hand side problem

Cyber-physical systems ..

.. and the role of models in them

The right-hand side problem ..

and how it's a problem

Behaviour-focused development ..

.. of large and small structures

Concerns and the right-hand side ..

.. in the large, in the small

How behaviour focus helps RHS ..

.. and why it can interest WG2.3

Cyber-physical systems: the world and the machine

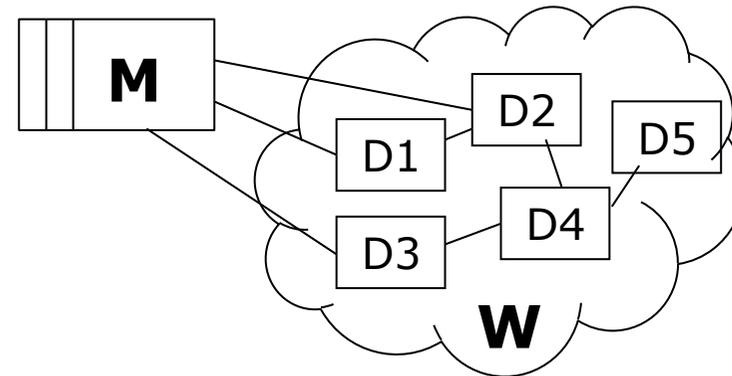
* 'physical' = non-formal world

* Radiation Therapy, Flight Control, Railway Interlocking, Passenger Lift, Vending Machine, Industrial Press, Car Park, Automotive, ...

* For Software Engineering

- * The physical world **W** is given
 - * Domains causally linked (–) ..
 - * .. by shared phenomena
 - * Human participants are domains
- * SE adds designed machine **M**
 - * Causally linked to **W**
 - * Governs **W**'s behaviour

* 'cyber' = governing behaviour



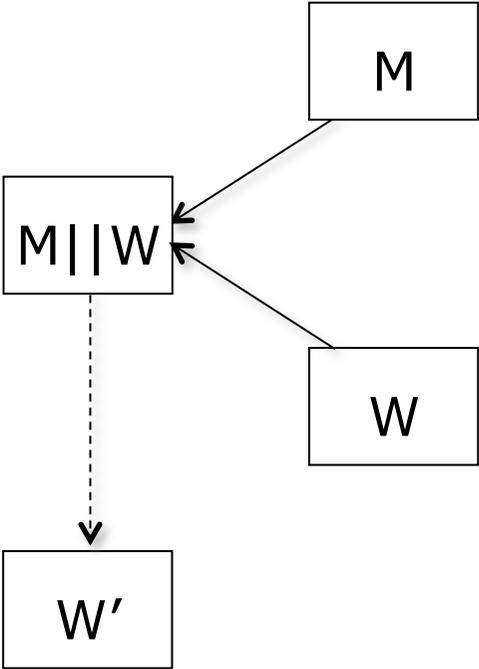
* This is Engineering BY Software

* Engineering OF Software is needed too

M, the given world W, and governed behaviour W'

M||W is the behaviour (B) of the system

W' is the behaviour of W governed by M

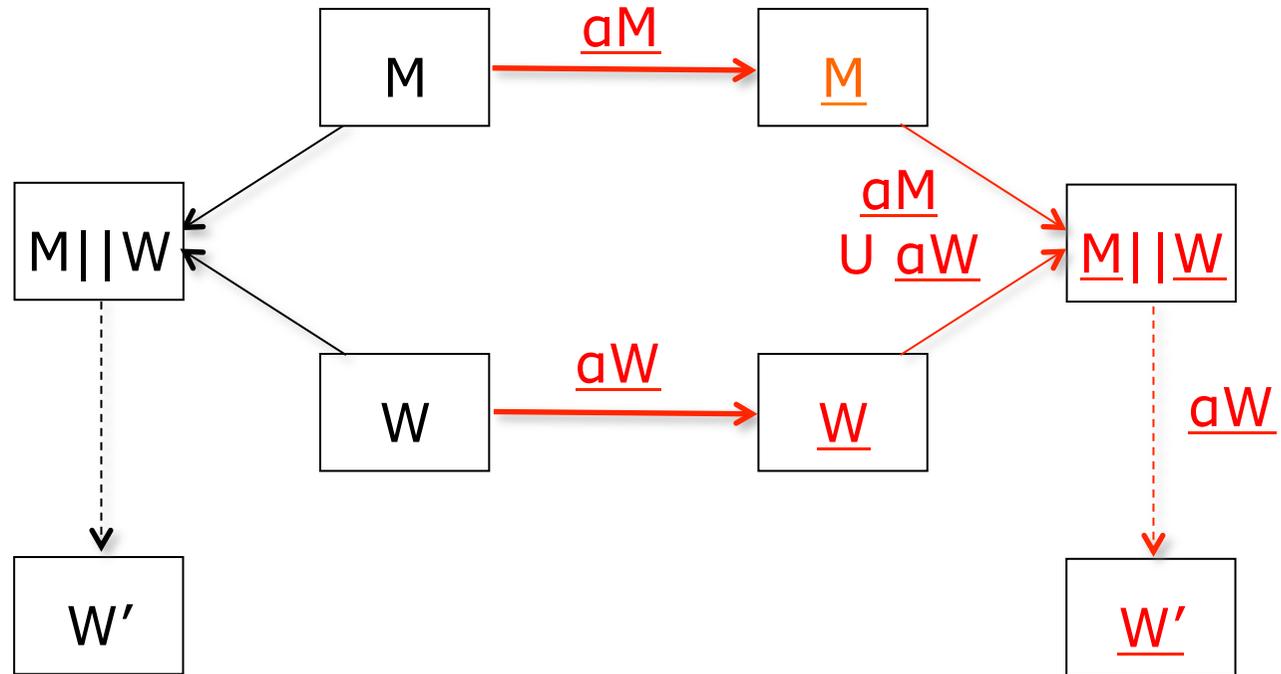


governed behaviour W': what can happen in W constrained by M||W

Models of M, given world W, and governed behaviour W'

M||W is the behaviour (B) of the system

W' is the behaviour of W governed by M



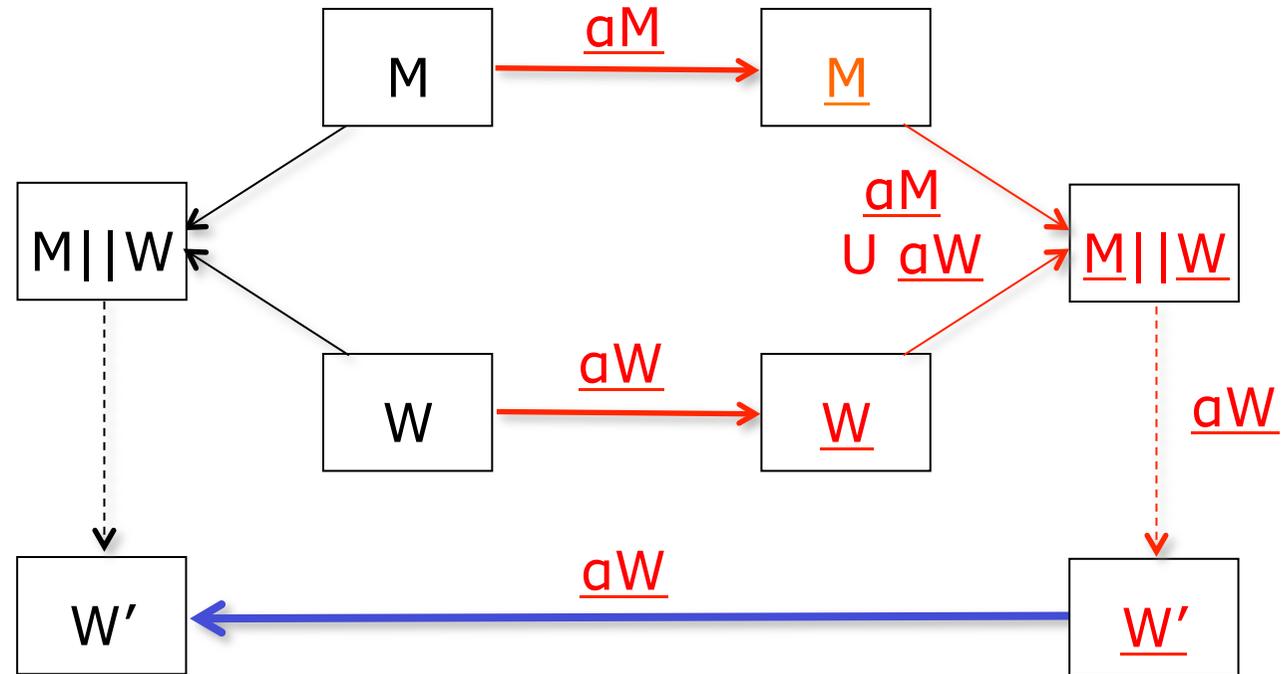
$\underline{M||W}$ is a closed model of M and W (interacting only with each other)

\underline{aM} is alphabet of \underline{M} , \underline{aW} is alphabet of \underline{W} (alphabets are the basis of interpretations)

The governed behaviour model \underline{W}' and the reality W'

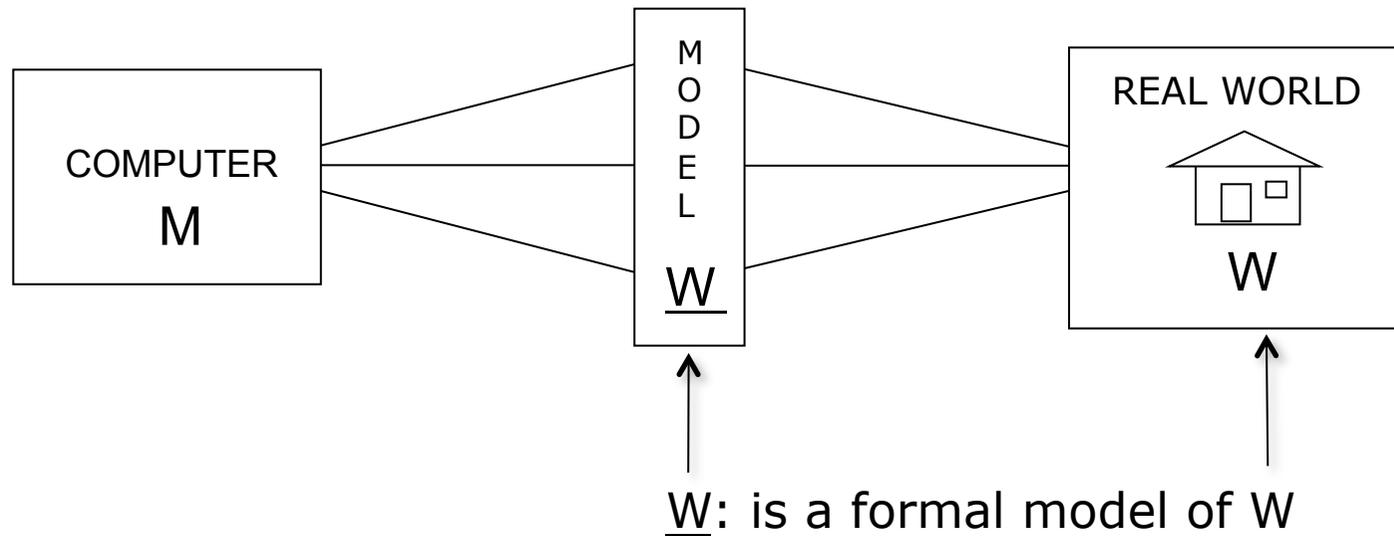
$M||W$ is the behaviour (B) of the system

W' is the behaviour of W governed by M



\underline{W}' should correctly predict W' (ie have same traces wrt \underline{aW})

The Right-Hand Side problem (Cantwell Smith*)



Left-Hand Side is rarely problematic
(Relationship between M and W)

The Right-Hand Side is problematic
(Relationship between W and W)

* Brian Cantwell Smith:
The Limits of Correctness, 1985

How is the Right-Hand Side problematic?

The Real World

- * No truly atomic phenomena
 - * TMI valve failure to close
- * Values are never exact
 - * Proton therapy gantry creep
- * Relevance is unbounded
 - * BMEWS and BMW brake
- * Recursively contingent causality
 - * Comet 1 fuselage testing
- * **Exaggeration! Some formal models do work quite well!**

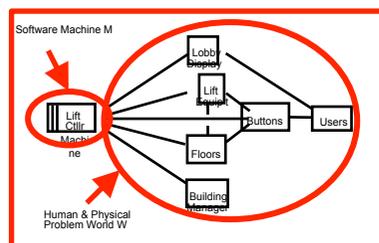
Formal Models

- * **Atomic ground terms**
- * **Exact real values**
- * **Invulnerable properties**
- * **Support formal proof**
- * Behaviour-based structuring mitigates the RHS problem

Behaviour-based structure (for RHS and other problems)

- * Purpose of software is governing system behaviour
 - * The behaviour itself is not a requirement
 - * Requirements are effects, results etc of behaviours
- * System behaviour combines constituent behaviours B_i
 - * Coherent and purposeful processes $B_i ::= \underline{W_i} \parallel \underline{M_i}$
 - * Constituent behaviours satisfy simplicity criteria
 - * Behaviour is governed by cause-and-effect links
- * Dynamic tree of enactments: nodes M_i ; edges (M_i, M_j)
 - * Parent M_i instantiates and controls M_j execution
 - * Execution of M_j governs enactment of behaviour B_j
 - * Standard protocols (as for procedure invocation) etc

System behaviour: combining constituent behaviours



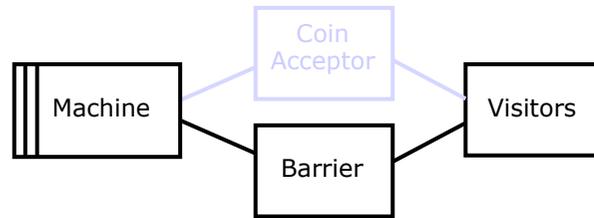
Behaviour B_i
 $::= M_i || W_i$

- Behaviour structure illustrated here by automotive features
 - Engine management is running: controlling mixture, throttle, etc
 - ABS is running: monitoring wheel speeds ready for braking
 - Stop-Start, Automatic Parking: no running instance now
 - Cruise Control is running: maintaining driver's chosen speed
 - Lane Departure Warning is running: watching lane markings
 - Speed Restriction is running: limiting speed to 110kph
 - Active Suspension is running: smoothing and stabilising ride
 - Air conditioning is running: cooling interior air
 -

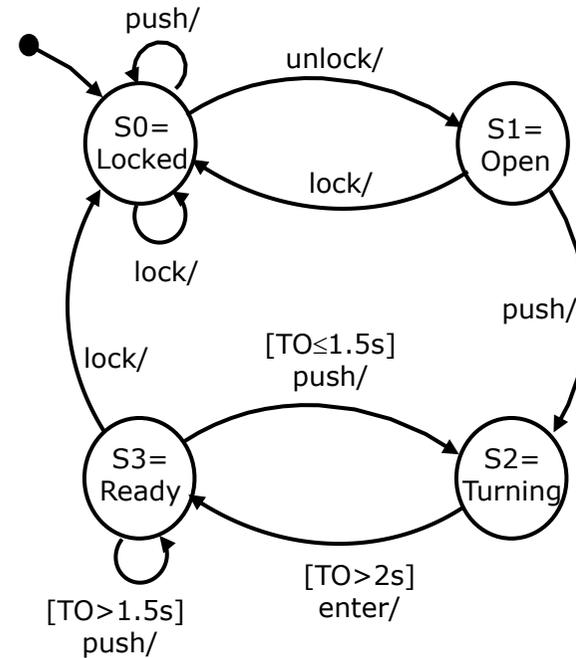
Developing behaviour-based structure

- * Development order is chiefly bottom-up
 - * Useful high-level abstractions are few (or absent) in CPS
 - * Combination demands prior understanding of components
 - * Combination may be invasive (W has no compositionality)
- * Constituent behaviours are initially developed in isolation
 - * Separating intrinsic from combinational complexity
 - * Combination is a distinct design activity
- * Checklists of concerns avoid known potential failures
 - * cf programming concerns (null-deref, store leak, o'flow, etc)
 - * Simple concerns, combination concerns ..
 - * .. overlapped and extended by modelling concerns

Simple concerns: initialisation, breakage, totality



M! {lock, unlock}
V! {push, enter}



- * Initialisation concern:
 - * When M_i execution starts, what is the state of W_i ?
- * Breakage concern:
 - * Domain vulnerability to every alphabet event?

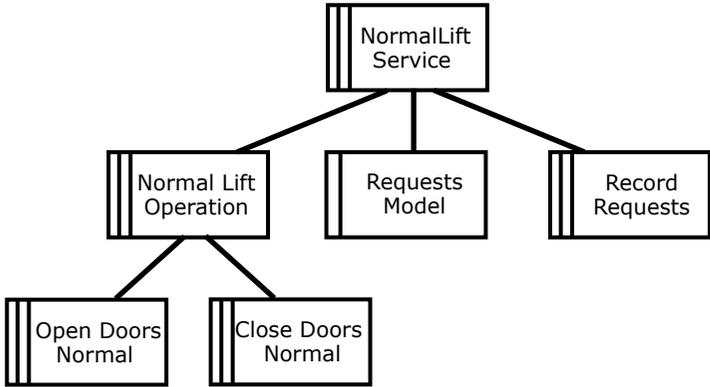
- * Totality concern:
 - * Possible effect of every alphabet event in every alphabet state?

Combination concerns: conflict, mutex, switching



- * Conflict concern:
 - * Conflicting demands on W state from B_i, B_j

- * Mutual exclusion concern:
 - * Simultaneous demands to 'read'/'write' W by B_i, B_j



- * Switching concern:
 - * Match W terminal state of B_i to initial state for B_j

Modelling concerns: granularity, creep, frame cond'n



event *pass*
g1: person p in room r
g2: p authorised for s
a1: p in s

- * Granularity concern:
 - * Atomic alphabet designations
 - * Unicontrol abstraction

- * Creep concern:
 - * Iterated "set position to P ; $P := \text{position}$ "
for real position, floating-point P



W: "move!" $\implies accel \implies \uparrow torque$
M: $\uparrow torque \implies$ "move!"
 $\implies release-brake$

- * Frame condition concern:
 - * Dual completeness at each
node in cause/effect graph

How behaviour focus helps RHS

- * Directly addresses 'how it works' and 'does it work?'
 - * System success and failure are causal success and failure
- * Behaviours support effective localisation of concerns
 - * Components are small, simple, closed, comprehensible
- * Wi and Mi are developed hand-in-hand (as they must be)
 - * W'i makes no sense without Mi (and *vice versa*)
- * Alphabet designations compel conscious granularity choices
 - * Explicitly designated phenomena, causal relations, domains
- * Wi is a minimal 'axiomatic' model, primarily causal
 - * Requirements satisfaction shown by 'theorems' in Wi
 - * Enactment tree and Wi provide maps to explore reliability

Why it can be interesting to WG2.3

- * The behaviour approach is a work in progress
 - * The work presented is 'pre-formal'
 - * 'Pre-formal' work must be followed by formal work
- * Formal language is needed for causal models
 - * Can temporal logics be enough?
 - * A discipline of 'operational principles'?
- * Enactment tree still very roughly sketched
 - * Parent-child control protocols invite study
 - * Relationship between W_i and M_i in enactment tree
- * A meeting place for practitioners and researchers?
 - * A long-standing need?

Thank you

